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Notes for Meeting 23 Three Paradigms for Plan Understanding Plan Understanding AI researchers have explored three main approaches to interpreting other agents' plans: Understanding Others' Behavior - Deductive approaches (e.g., Kautz & Allen, 1986), which aim to prove the agent was pursuing one of a set of plans. Although most AI research on plans and action has focused on generation, humans are also able to understand other's actions. - These support rich representations but require enough knowledge to eliminate most alternatives. This capacity, sometimes called plan understanding, plays a key role in our ability to interact with others. - Probabilistic approaches, which attempt to find the most probable plan given the observations. Plan understanding lets us construct models of other agents' mental states based on their observed activities. - These typically rely on variants of hidden Markov models and assume limited representations. Intelligent agents that lack this ability are doomed to treat other agents as objects without beliefs, goals, or intentions. - Abductive approaches, which aim to find one or more plausible acounts of the agent's behavior. Applications of Plan Understanding - These support rich representations but do not require probabilities The task of plan understanding arises in many different situations: and do not need to disprove alternatives. - socially-constrained physical activities like driving and walking Both the deductive and abductive frameworks can benefit from structural - competitive activities like sports, board games, and computer games knowledge, such as HTN methods. - inferring enemry intentions in support of military planning - coordinating complex joint activities with other agents Understanding Multi-Agent Interactions - appreciating comedies and dramas on television - carrying out an extended dialogue with another agent Some settings require one to understand observed behavioral interactions that occur among multiple agents. The ability to understand other agents' plans is a distinguishing feature of human intelligence. These require the ability to represent and reason about more embedded structures than single-agent behavior, such as: The Task of Plan Understanding - (goal Joe (loves Mary Joe)) We can define the task of plan understanding semi-formally as: - (belief Joe (goal Mary (loves Sam Mary)) - (goal Mary (loves Joe Mary)) - Given: Background knowledge about actions and/or plans that can occur in some domain. An agent observing Joe, Mary, and Sam must infer not only their beliefs - Given: An observed sequence of states traversed / actions taken and goals, but their beliefs about each others' belief and goals. by another agent. - Find: One or more plans that account for the observed behavior Misunderstandings are the basis for many comedies and tragedies, which in terms of background knowledge. we appreciate because we can interpret them. This task is substantially more challenging that activity recognition, Understanding and Learning which involves assigning observed behavior to some activity class. Plan understanding also provides a source of material to drive learning. Forms of Knowledge for Plan Understanding - Given: Background knowledge about actions and/or plans that can Methods for plan understanding must encode background knowledge in occur in some domain. some form, such as: - Given: An explanaiton for an observed sequence of states traversed / actions taken by another agent. - the conditions and effects of domain actions - Find: New hierarchical skills or methods that let one interpret - hierarchical structures like HTN methods similar situations or generate similar behavior. - specific plans that have occurred in the past Such analytical approaches to learning acquire knowledge far more rapidly than empirical / statistical methods. In general, richer forms of background knowledge make the task of plan understanding more tractable.

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Assignments for Meeting 24 Cognition, Affect, and Emotion

Read the article:

- \* Marsella, S., Gratch, J., & Petta, P. (in press). Computational models of emotion. In Scherer, K. R., Bnziger, T., & Roesch, E. (Eds.), A blueprint for an affectively competent agent: Crossfertilization between emotion psychology, affective neuroscience, and affective computing. Oxford: Oxford University Press. [required]
- \* Simon, H. A. (1967). Motivational and emotional controls of cognition. Psychological Review, 74, 29-39. [optional]
- \* Marinier, R., & Laird, J. (2004). Towards a comprehensive computational model of emotions and feelings. Proceedings of the Sixth International Conference on Cognitive Modeling. Pittsburgh, PA. [optional]